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① $u(\vec{x}, t) = -\alpha x_0 e^{-\alpha t}$, $v(\vec{x}, t) = y_0 e^{\alpha t}$ (Lagrangian velocity)

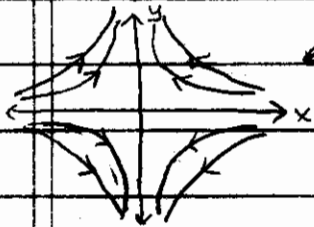
$u(\vec{x}, t) = -\alpha x$, $v(\vec{x}, t) = \alpha y$ (Eulerian velocity)

Use the streamlines equation, $\frac{dy}{dx} = \frac{v}{u} = -\frac{y}{x} \Rightarrow y = \frac{C_1}{x}$, or

use the fact that for time-independent flows

(i.e., time-independent Eulerian velocity fields)

streamlines are path lines so $y = \frac{y_0 x_0}{x}$ for the streamlines



← A few streamlines

② See attached figures.

To do a rough and dirty fit of the equatorial Pacific data to $T(z) = T_0 + T_1 e^{-z/h}$,

i. Find $T_0 = 1.2^\circ\text{C}$

ii. $T_0 + T_1 e^{-500\text{m}/h} = 8.3^\circ\text{C} \Rightarrow T_1 e^{-500\text{m}/h} = 8.3 - 1.2 = 7.1^\circ\text{C}$

iii. $T(z=500+h) = T_0 + T_1 e^{-(500+h)/h} = T_0 + (T_1 e^{-500/h}) e^{-1}$
 $= 1.2 + 7.1 e^{-1} = 3.8^\circ\text{C}$

$T(z=500+h) = 3.8^\circ\text{C}$ gives $500+h = 1100 \Rightarrow h = 600\text{m}$ from data

iv. $T_1 = 7.1 e^{500\text{m}/h} = 7.1 e^{5/6} = 16.3^\circ\text{C}$

(I used 3 data points to approximate T_0, T_1, h)

Note that $T = 1.2^\circ\text{C} + 16.3^\circ\text{C} e^{-z/600\text{m}}$ looks similar to data

in attached figures.

$\frac{dT}{dt} = \frac{\partial T}{\partial t} + \vec{u} \cdot \nabla T = K \nabla^2 T \Rightarrow w T_z = K T_{zz}$ when $u=v=0, T_x=T_y=0$

$K = hw = 600\text{m} \cdot 10^{-4} \text{cm/s} = 6 \frac{\text{cm}^2}{\text{s}} = 6 \cdot 10^{-4} \frac{\text{m}^2}{\text{s}}$

② cont'd

North Atlantic: $T(z) = 3.4^\circ\text{C} + 9.8^\circ\text{C} e^{-z/500\text{m}} \Rightarrow K = 5 \frac{\text{cm}^2}{\text{s}}$

Southern Ocean: $T(z) = 0.8^\circ\text{C} + 9.3^\circ\text{C} e^{-z/950\text{m}} \Rightarrow K = 9.5 \frac{\text{cm}^2}{\text{s}}$

The same K, w don't fit all 3 temperature profiles. Both the vertical velocity and the vertical mixing coefficient vary from place to place in the ocean.

③ a) see attached plot

b) $\frac{\partial T}{\partial y} = \frac{8 - 22^\circ\text{C}}{54 - 310\text{km}} = -0.6 \frac{^\circ\text{C}}{\text{km}} = -0.6 \cdot 10^{-2} \frac{^\circ\text{C}}{\text{km}}$

c) $\frac{dT}{dt} = \frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + w \frac{\partial T}{\partial z} = 0.1 \frac{\text{m}}{\text{s}} (-0.6 \cdot 10^{-2} \frac{^\circ\text{C}}{\text{km}}) = -0.05 \frac{^\circ\text{C}}{\text{day}}$

⑤ $\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -\mu & -\Omega \\ \Omega & \mu \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$

define $\vec{M} = \begin{pmatrix} -\mu & -\Omega \\ \Omega & \mu \end{pmatrix}$

The solution is $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} e^{\vec{M}t}$, where $e^{\vec{M}t} \equiv U e^{\lambda t} U^{-1}$
 $U \equiv \begin{pmatrix} (\mu+\lambda)/\Omega & (\mu-\lambda)/\Omega \\ -1 & -1 \end{pmatrix}$, $e^{\lambda t} \equiv \begin{pmatrix} e^{-\lambda t} & 0 \\ 0 & e^{\lambda t} \end{pmatrix}$, $\lambda \equiv \pm \sqrt{\mu^2 - \Omega^2}$

This is one of many ways to solve the linear coupled ordinary differential equations, and it illustrates the solution's dependence on $e^{\pm \lambda t}$, where $\pm \lambda$, defined

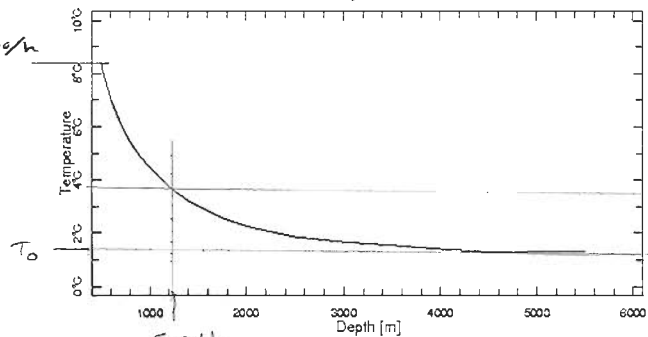
above, are the eigenvalues of \vec{M} . If $\mu > \Omega$, the exponential is real, and the motion is unstable

(blows up like $e^{\sqrt{\mu^2 - \Omega^2} t}$). If $\Omega > \mu$, the exponential is imaginary, and the motion is oscillatory (oscillates like $e^{i\sqrt{\Omega^2 - \mu^2} t} = \cos \sqrt{\Omega^2 - \mu^2} t + i \sin \sqrt{\Omega^2 - \mu^2} t$).

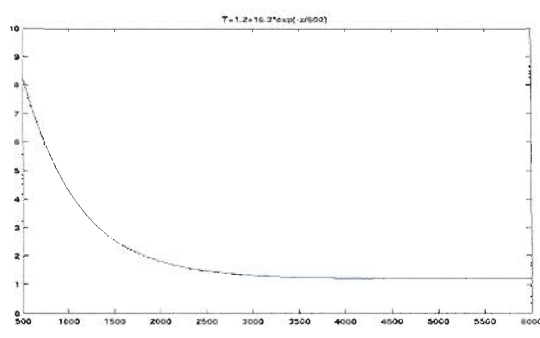
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EQUATORIAL PACIFIC

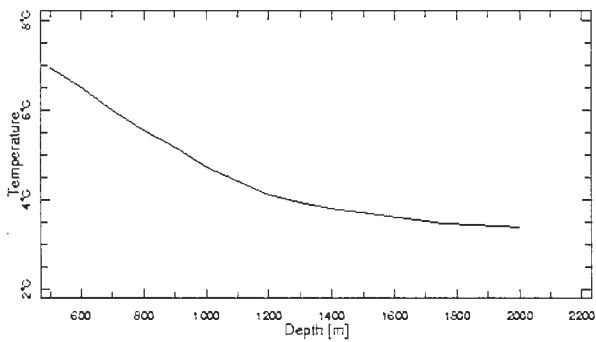
$$T_0 + T_1 e^{-5.0g/h}$$



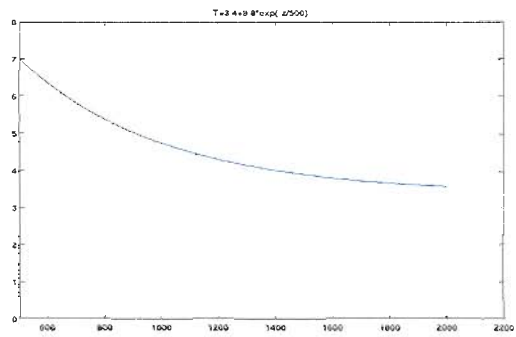
170.5W 0.5S



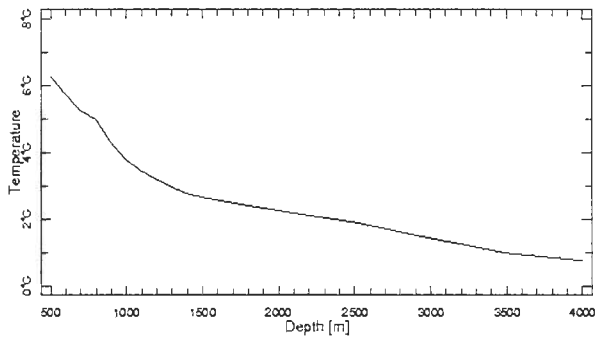
NORTH ATLANTIC



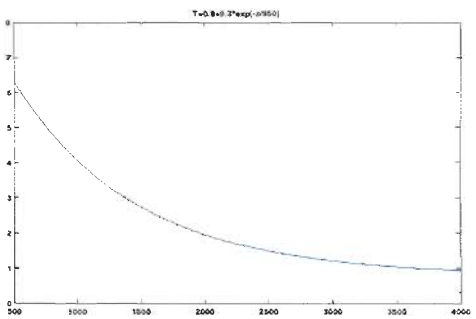
25.5W 59.5N



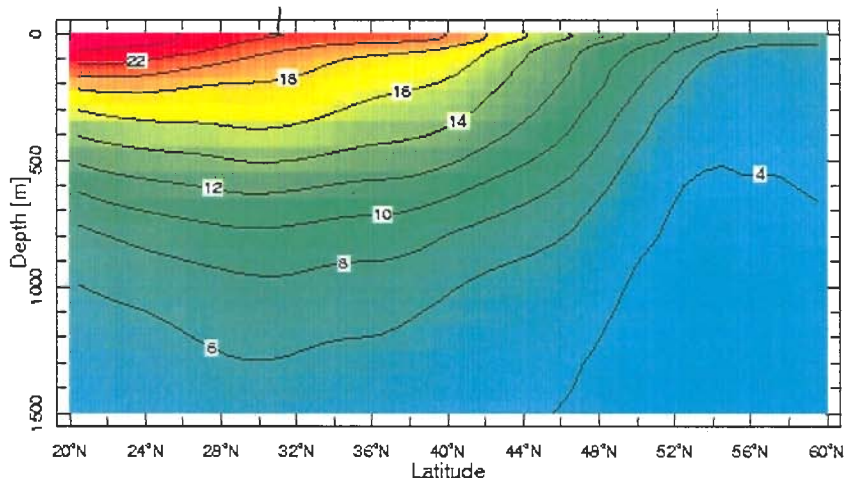
SOUTHERN OCEAN



149.5E 50.5S



3



40.5W